What Is Claimed Is:

- 1. A method for controlling a driver-assistance device, in which measured quantities to be recorded by sensors are evaluated for triggering a reaction, and measuring instants are determined through essentially repeating cycles for acquiring and evaluating the measured quantities, wherein the measuring instants are controlled in such a way that one of the measuring instants follows as immediately as possible an instant at which measured quantities giving rise to a triggering probably exist.
- The method as recited in Claim 1,
 wherein the measuring instants are controlled as a function of a prediction of the instant.
- 3. The method as recited in one of Claims 1 or 2, wherein faster algorithms are used for predicting the instant than for triggering the reaction.
- 4. The method as recited in one of the preceding claims, wherein the measuring instants are controlled by altering the run length of computer programs for evaluating the measurement data.
- The method as recited in Claim 4,
 wherein the run length is altered via the number of refresh cycles.
- 6. The method as recited in one of Claims 1 through 5, wherein the reaction is an intervention into the guidance of the vehicle.
- 7. The method as recited in one of the preceding claims, wherein the reaction includes warning signals.
- 8. The method as recited in one of the preceding claims, wherein the reaction includes occupant restraint measures.
- 9. A system for controlling a driver-assistance device, in which measured quantities acquired by sensors (12, 13) are evaluated for triggering a reaction, and measuring instants are determined through essentially repeating cycles for acquiring and evaluating the measured quantities,

NY01 1041385 v1 6

wherein means (11) are provided which control the measuring instants in such a way that one of the measuring instants follows as immediately as possible an instant at which measured quantities giving rise to a triggering probably exist.

- 10. The system as recited in Claim 9, wherein the measuring instants are controlled as a function of a prediction of the instant
- 11. The system as recited in one of Claims 9 or 10, wherein at least one of the sensors is a radar sensor (13).
- 12. The system as recited in one of Claims 9 or 10, wherein at least one of the sensors is a video sensor (12).
- 13. The system as recited in one of Claims 9 or 10, wherein at least one of the sensors is a lidar sensor.

NY01 1041385 v1 7